USN

10ME/PM82

## Eighth Semester B.E. Degree Examination, Dec.2016/Jan.2017 Control Engineering

Time: 3 hrs.

Max. Marks:100

Note: Answer FIVE full questions, selecting at least TWO questions from each part.

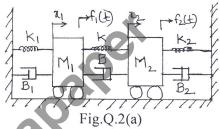
## PART - A

- 1 a. Define: i) System; ii) Controller; iii) Open loop system; iv) Closed loop system; v) Feed back, with examples. (05 Marks)
  - b. With the help of block diagram, explain i) PI ii) PID.

(10 Marks)

- c. List the advantages and disadvantages of i) Proportional controller; ii) Integral controller.

  (05 Marks)
- 2 a. Write the differential equations governing the mechanical system shown. Also draw F-V and F-C analogous circuits. (14 Marks)



b. Obtain the transfer function for the given thermal system.

(06 Marks)

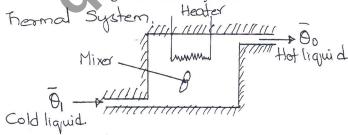
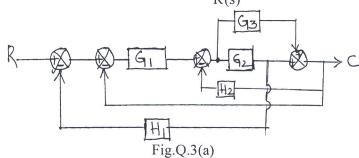


Fig.Q.2(b)

3 a. Reduce the block diagram and obtain control ratio  $\frac{C(s)}{R(s)}$ . (10 Marks)



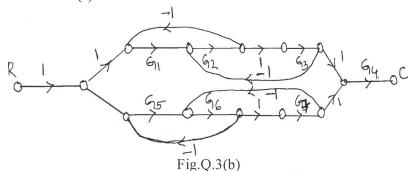
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b. Obtain the overall TF  $\frac{C(s)}{R(s)}$  of the SFG given:

(10 Marks)



- 4 a. Define: i) Time response; ii) Step signal; iii) Ramp signal; iv) Parabolic signal; v) Impulse signal. (05 Marks)
  - b. Derive an expression for response of 1<sup>st</sup> order system for unit step input. (05 Marks)
  - c. A unity feedback CS has an OLTF  $G(s) = \frac{10}{s(s+2)}$ . Find tr, %M<sub>p</sub>, t<sub>p</sub>, t<sub>s</sub> for a step input of 12 units.
  - d. Using R-H criterion, determine the stability of the system represented by the characteristic equation  $s^5 + 4s^4 + 8s^3 + 8s^2 + 7s + 4 = 0$ . (05 Marks)

PART - B

5 a. Construct a Nyquist plot for a feedback control system whose OLTF is given by  $G(s)H(s) = \frac{5}{s(1-s)}$ . Comment on the stability of open loop and closed loop system.

(14 Marks)

- b. Define with respect to Nyquist plot, i) Gain Margin; ii) Phase Margin; iii) Relative stability. (06 Marks)
- Sketch the bode plot for the following TF and determine phase margin and gain margin.  $G(s) = \frac{75(1+0.2s)}{s(s^2+16s+100)}.$ (20 Marks)
- 7 Sketch the root locus for UFB system whose open loop TF.

$$G(s) = \frac{K}{s(s^2 + 6s + 10)}.$$
 (20 Marks)

- 8 a. Define: i) State; ii) State variables; iii) State space; iv) State trajectory; v) State vector.
  - b. Write a note on: i) Lag compensator; ii) Lead compensator. (05 Marks) (10 Marks)
  - c. Explain the following terms with examples: i) Controllability; ii) Observability. (05 Marks)

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